Bluetooth Robots

Have 2 robots, one with a color sensor, and one without it.

Run the program on the robot with the color sensor:
- Have it say the Communication's sound Hello, set its LED status to Red.
- Wait for the other robot to send a start command before continuing.
- Once Bluetooth has connected, set the LED to Green.

Run the program on the robot without the color:
- Send a command to the other robot, so the other robot can start.
- Have it say the Communication's sound Okey-Dokey, set its LED status to Green.

Have an infinite loop on the robots so that:
When a Red/Yellow/Green/Blue item is in front of the robot with the color sensor, the 2nd robot (that does not have a color sensor) will say the color.

Extras:
Can you turn the 1st robot’s buttons into a remote control for the 2nd? Forward/Back/Turn Left/Turn Right, and then center button act as a horn?