

## ARTIFICIAL INTELLIGENCE & AGENTS

### What is AI?

- AI is both science and engineering:
  - the *science* of understanding intelligent entities — of developing theories which attempt to explain and predict the nature of such entities;
  - the *engineering* of intelligent entities.

- Four views of AI:

1. AI as *acting humanly*
  - as typified by the Turing test
2. AI as *thinking humanly*
  - cognitive science.
3. AI as *thinking rationally*
  - as typified by logical approaches.
4. AI as *acting rationally*
  - the intelligent agent approach.

### Acting Humanly

- A problem that has greatly troubled AI researchers: *when can we count a machine as being intelligent?*
- Most famous response due to Alan Turing, British mathematician and computing pioneer:



Human interrogates entity via teletype for 5 minutes. If, after 5 minutes, human cannot tell whether entity is human or machine, then the entity must be counted as intelligent.

- No program has yet passed Turing test!  
(Annual Loebner competition & prize.)
- A program that succeeded would need to be capable of:
  - natural language understanding & generation;
  - knowledge representation;
  - learning;
  - automated reasoning.
- Note no *visual* or *aural* component to basic Turing test — augmented test involves video & audio feed to entity.

### Thinking Humanly

- Try to understand how the mind works — how do we think?
- Two possible routes to find answers:
  - by *introspection* — we figure it out ourselves!
  - by *experiment* — draw upon techniques of psychology to conduct controlled experiments. (“Rat in a box”!)
- The discipline of *cognitive science*: particularly influential in *vision*, *natural language processing*, and *learning*.

### Thinking Rationally

- Trying to understand how we *actually* think is one route to AI — but how about how we *should* think.
- Use *logic* to capture the *laws of rational thought* as *symbols*.
- *Reasoning* involves shifting symbols according to well-defined rules (like algebra).
- Result is *idealised* reasoning.
- Logician approach theoretically attractive.

- Lots of problems:
  - *transduction* — how to map the environment to symbolic representation;
  - *representation* — how to represent real world phenomena (time, space, ...) symbolically;
  - *reasoning* — how to do symbolic manipulation *tractability* — so it can be done by real computers!
- We are still a long way from solving these problems.
- In general logic-based approaches are unpopular in AI at the moment.

## Acting Rationally

- Acting rationally = acting to achieve one's goals, given one's beliefs.
- An *agent* is a system that perceives and acts; intelligent agent is one that acts rationally w.r.t. the goals we delegate to it.
- Emphasis shifts from designing *theoretically best* decision making procedure to best decision making procedure possible in circumstances.
- Logic may be used in the service of finding the best action — not an end in itself.

- Achieving *perfect* rationality — making the best decision theoretically possible — is not usually possible, due to *limited resources*:
  - limited time;
  - limited computational power;
  - limited memory;
  - limited or uncertain information about environment.
- The trick is to *do the best with what you've got!*
- This is easier than doing perfectly, but still tough.

## Brief History of AI

### 1943–56:

- McCulloch & Pitts (1943)  
artificial neural net — proved equivalent to Turing machine;
- Shannon, Turing (1950)  
chess playing programs
- Marvin Minsky (1951)  
first neural net computer — SNARC
- Dartmouth College (1956)  
term "AI" coined by John McCarthy  
Newell & Simon presented LOGIC THEORIST program

### 1956-70:

- Programs written that could:  
plan, learn, play games, prove theorems, *solve problems*.
- Major centres established:
  - Minsky — MIT
  - McCarthy — Stanford
  - Newell & Simon — CMU
- Major feature of the period were *microworlds* — toy problem domains.  
Example: blocks world.  
“It’ll scale, honest...”

### 1970s:

- 1970s period of recession for AI  
(Lighthill report in UK)
- Techniques developed on microworlds *would not* scale.
- Implications of *complexity theory* developed in late 1960s, early 1970s began to be appreciated:
  - *brute force techniques will not work.*
  - *works in principle does not mean works in practice.*

### 1980s:

- General purpose, brute force techniques don’t work, so use *knowledge rich* solutions.
- Early 1980s saw emergence of *expert systems* as systems capable of exploiting knowledge about tightly focussed domains to solve problems normally considered the domain of experts.
- Ed Feigenbaum’s *knowledge principle*:  
[Knowledge] is power, and computers that amplify that knowledge will amplify every dimension of power

- Expert systems success stories:
  - MYCIN — blood diseases in humans;
  - DENDRAL — interpreting mass spectrometers;
  - R1/XCON — configuring DEC VAX hardware;
  - PROSPECTOR — finding promising sites for mineral deposits;
- Expert systems emphasised *knowledge representation*: rules, frames, semantic nets.
- Problems:
  - the knowledge elicitation bottleneck;
  - marrying expert system & traditional software;
  - breaking into the mainstream.

### Early 1990s:

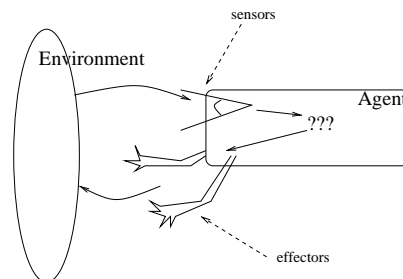
- Most companies set up to commercialise expert systems technology went bust.
- “AI as homeopathic medicine” viewpoint common.
- 1990s: emphasis on understanding the interaction between *agents* and *environments*.
- AI as *component*, rather than as end in itself.
  - “Useful first” paradigm — Etzioni (NETBOT, US\$35m)
  - “Raisin bread” model — Winston.

### Late 1990s onwards:

- Increased interest in machine learning
  - Reaction against expert systems?
- Rise of statistical methods.
- Agent paradigm becomes commonplace.
- Robotics for the masses.

### Intelligent Agents

- An *agent* is a system that is *situated* in an environment, and which is capable of *perceiving* its environment and *acting* in it to satisfy its design objectives.
- Pictorially:



- Human “agent”:
  - *environment*: physical world;
  - *sensors*: eyes, ears, ...
  - *effectors*: hands, legs, ...
- Software agent:
  - *environment*: (e.g.) UNIX operating system;
  - *sensors*: `ls`, `ps`, ...
  - *effectors*: `rm`, `chmod`, ...
- Robot:
  - *environment*: physical world;
  - *sensors*: sonar, camera;
  - *effectors*: wheels.

## What to do?

Those who do not reason  
Perish in the act.  
Those who do not act  
perish for that reason  
(W H Auden)

- The key problem we have is *knowing the right thing to do*.
- Knowing what to do can *in principle* be easy: consider all the alternatives, and choose the “best”.
- But any time-constrained domain, we have to make a decision *in time for that decision to be useful!*
- A tradeoff.

## • Ideal rational agent:

For each percept sequence, an ideal rational agent will act to maximise its expected performance measure, on the basis of information provided by percept sequence plus any information built in to agent.

- Note that this does not preclude performing actions to *find things out*.
- More precisely, we can view an agent as a function:

$$f : P^* \rightarrow A$$

from sequences of percepts  $P$  to actions  $A$ .

## Accessible vs inaccessible

An accessible environment is one in which the agent can obtain complete, accurate, up-to-date information about the environment's state.

Most moderately complex environments (including, for example, the everyday physical world and the Internet) are inaccessible.

The more accessible an environment is, the simpler it is to build agents to operate in it.

## Deterministic vs non-deterministic

A deterministic environment is one in which any action has a single guaranteed effect — there is no uncertainty about the state that will result from performing an action.

The physical world can to all intents and purposes be regarded as non-deterministic.

Non-deterministic environments present greater problems for the agent designer.

### Episodic *vs* non-episodic

In an episodic environment, the performance of an agent is dependent on a number of discrete episodes, with no link between the performance of an agent in different scenarios.

An example of an episodic environment would be a mail sorting system.

Episodic environments are simpler from the agent developer's perspective because the agent can decide what action to perform based only on the current episode — it need not reason about the interactions between this and future episodes.

### Static *vs* dynamic

A static environment is one that can be assumed to remain unchanged except by the performance of actions by the agent.

A dynamic environment is one that has other processes operating on it, and which hence changes in ways beyond the agent's control. The physical world is a highly dynamic environment.

### Discrete *vs* continuous

An environment is discrete if there are a fixed, finite number of actions and percepts in it.

Russell and Norvig give a chess game as an example of a discrete environment, and taxi driving as an example of a continuous one.

### Summary

- This lecture has looked at:
  - The history of AI
  - The notion of intelligent agents
  - A classification of agent environments.
- Broadly speaking, the rest course will cover the major techniques of AI, with special reference to agents.
- The techniques we'll look at will start with those applicable to simple environments and move towards those suitable for more complex environments.