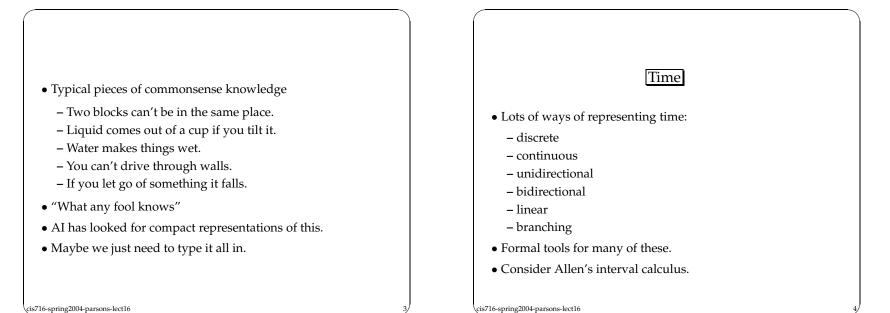
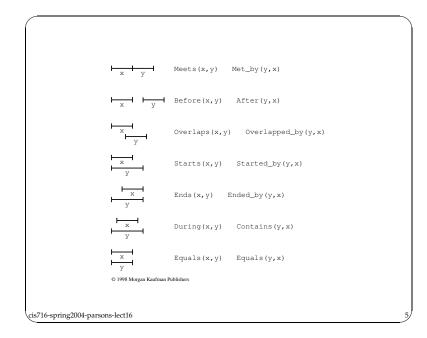
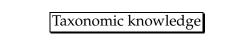
COMMONSENSE KNOWLEDGE

What is commonsense knowledge?

- Throughout, we have talked to "domain knowledge", knowledge about the situation an agent finds itself in.
- It seems to be relatively easy to program th agent with good detailed knowledge about domains.
- (Dealing with the volume of knowledge is another question.)
- However, it is much harder to give agents the kind of general knowledge about the world that children have.
- (Perhaps because agents don't get to spend as much time learning about the world by interacting with it that children do.)
- Such knowledge is necessary, though, if we want to build general intelligent agents.







- Often we find that commonsense knowledge comes in the form of taxonomies.
- \bullet All $P\mathbf{s}$ are $Q\mathbf{s}.$

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• We can represent this as logic.

 $\begin{array}{l} Laser_printer(snoopy) \\ \forall x \cdot Laser_printer(x) \ \Rightarrow \ Printer(x) \\ \forall X \cdot Printer(x) \ \Rightarrow \ Office_machine(x) \end{array}$

- We can infer $\forall x \cdot Laser_printer(x) \Rightarrow Office_machine(x)$
- We can inherit properties from superclass to subclass.

- These map into logic

 ∀x, y · Meets(x, y) ≡ (end(x) = start(y))
 ∀x, y · Before(x, y) ≡ ∃z(Meets(x, z) ∧ Meets(z, y))

 And the rest can be defined in a similar manner.
 Then we can describe temporal aspects about the world:

 ∀y · Occurs(Flow, y) ⇒
 ∃x, z · Occurs(Turn, x) ∧ Occurs(Turn, y)
 ∧ Overlaps(x, y) ∧ Overlaps(y, z)

 We can then:

 Use a theorem prover to reason about the world.
 - Use a STRIPS planner to decide what to do.

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Semantic Networks

- Taxonomic reasoning can be more efficient not in logic.
- Developed by Quillian in 1968, for *semantic memory*.
- Models the "associations" between ideas that people maintain.
- Semantic net is a *labelled graph*.
 - nodes in graph represent *objects, concepts,* or *situations;*
 - arcs in graph represent *relationships between objects*.



• $x \xrightarrow{subset} y$ "x is a kind of y" (\subset) Example: penguin \xrightarrow{subset} bird

•
$$x \xrightarrow{member} y$$

"x is a y" Example: $opus \xrightarrow{member} penguin$

 $\bullet \; x \stackrel{R}{\longrightarrow} y$

"*x* is *R*-related to *y*" Example: $bill \xrightarrow{friend} opus$

• Inference is then by traversing arcs.

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- *Binary* relations are easy and natural to represent.
- Others kinds of relation are harder.
- Unary relations (properties). Example: "Opus is small".
- Three place relations. Example: "Opus brings tequila to the party."
- Some binary relations are problematic ... "Opus is larger than Bill."

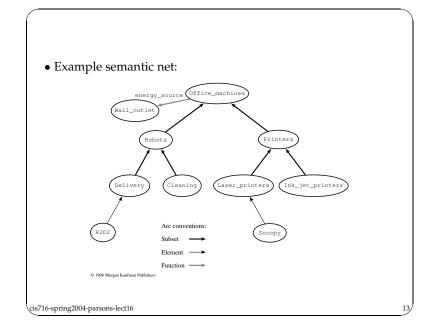


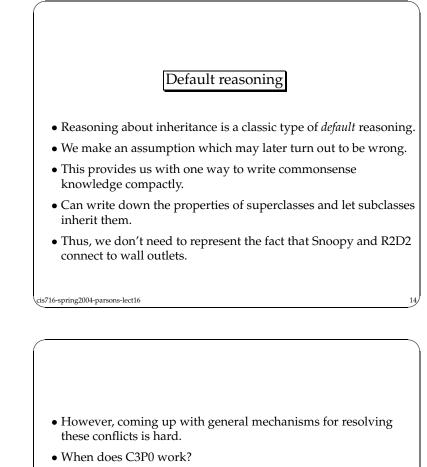
• *Quantified* statements are very hard for semantic nets.

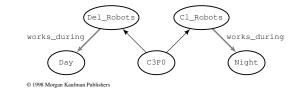
Examples:

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- "every dog has bitten a postman"
- "every dog has bitten every postman"
- *Partitioned* semantic nets can represent these.
- Of course, expressions like this are very easy to represent in first order logic.





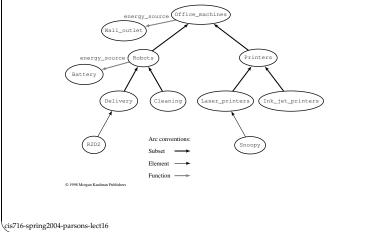


• Can add priorities/preferences to deal with this.

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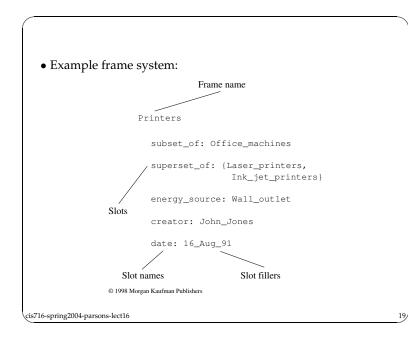
• We can also deal with inheritance conflicts:



Frames

- Frames are a kind of *structured* knowledge representation mechanism.
- All information relevant to a particular concept is stored in *frame* which resembles C struct, PASCAL record, Java object...
- Each frame has a number of *slots*.
- Each slot may be *filled* by:
 - a value;
 - a pointer to another frame;
 - a procedure.
- Slots may have *default values* associated with them.
- Frames = OO!

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- Frames are typically used to represent the *properties* of objects, and the relationships between them.
- Frames may represent:
 - *generic concepts* (cf classes) or
 - *specific items* (cf objects).
- Most important kind of link between frames:

is-a

- Facilitates reasoning about object properties.
- Allows *default values* to be *inherited*.

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- How to reason with frame systems?
- Easy to answer questions such as *is x a y*? Simply follow the *is-a* links.
- Example: Is snoopy a laser printer.
- (Problem of *multiple inheritance* Nixon diamond.)
- Also useful for *default* reasoning. Simply *inherit* all default values that are not explicitly provided.
- Example: Does snoopy the printer have a wall outlet?

- *Scripts* are a variant of frames, for representing *stereotypical sequences of events*.
- A script is thus a frame with a set of prescribed slots, for example:
 - Some initial conditions;
 - Some final conditions;
 - Some state description;
 - Some actions; and
 - Some actors
- The structure of the script is heavily domain dependent.

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... 10/ Customer leaves restaurant Main concept: 6 Results: Customer not hungry, Customer has less money, Restaurant has more money, Waiter gets tip

Jame	e: RESTAURANT
Role	es: Customer, Waiter, Cook, Cashier
Enti	ry condition: Customer is hungry
Prop	ps: Food, table, money, menu, tip
Ever	nts:
1/	Customer enters restaurant
2/	Customer goes to table
3/	Waiter brings menu
4/	Customer orders food
5/	Waiter brings food
6/	Customer eats food

- Scripts developed by Roger Schank for *understanding stories*.
- Used to help *understand language*.
- Scripts provide *context* information without which sentences cannot be understood:
 - sentences are not unconstrained sequences of words;
 - stories are not unconstrained sequences of sentences.
- Schank developed SAM (Script Applier Mechanism) that could *fill in gaps* in stories.
- Also able to "explain" elements of stories, e.g., people get upset or angry when story deviates from script.

Problems with Frames & Semantic Nets

- Both frames and semantic nets are essentially *arbitrary*.
- Both are useful for representing certain sorts of knowledge.
- But both are essentially *ad hoc* lack precise meaning, or *semantics*.
- Inference procedures poorly defined & justified.
- The *syntax* of KR scheme is *irrelevant*.
- *Logic* generalises these schemes... and that is both an advantage and a disadvantage.

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- Trying to make logic *nonmonotonic* has consumed a lot of work over the last 20 years.
- One of the best solutions (there is no one best solution) is the use of *argumentation*.
- We establish whether ϕ holds by looking at the reasons (arguments) that support it:

$$(\{a, a \Rightarrow b, b \Rightarrow c\}, c)$$

- We deal with conflict between deductions through the notion of *acceptability*
- Acceptable arguments are ones not attacked, or ones whose attackers are defeated.

- Logic has a(nother) problem, it is inherently *monotonic*
- Once we have:

 $\Delta \vdash \phi$

then

 $\Delta \cup \{\psi\} \vdash \phi$

whatever ψ may be.

- So, once we know that C3P0 is a delivery robot, and so works during the day nothing can refute this ...
- ... even when we are told that as a night delivery robot he works at night.

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Summary

- This lecture introduced the idea of commonsense knowledge in AI.
- It then briefly surveyed representations of time and taxonomic knowledge, before talking about the general problem of nonmonotonic reasoning.
- Finally the lecture mentioned argumentation as a general approach to nonmonotonic reasoning.