Evolution and Co-Evolution of Computer Programs to Control Independently-Acting Agents

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Outline

Introduction Genetic Programming Paradigm ♦3 examples - Artificial Ant - Differential Game - Co-Evolution Game

Introduction

For some particular problems, genetic programming paradigm can genetically breed the fittest computer program to solve these problems.

Genetic Programming Paradigm:

- Using hierarchic genetic algorithm by specifying:
 - The structures
 - The search space
 - The initial structure
 - The fitness function

Genetic Programming Paradigm: (Cont)

- The operation that modify the structure
 - the fitness proportionate reproduction
 - the crossover(recombination)
- The state of the system
- Identifying the results and termination the algorithm
- The parameters that control the algorithm

Artificial Ant Trail



A toroidal grid plane with 32*32 cells on which a winding trial consists of 89 stones, where there are single, double, and triple missing stones on the trail.

♦ Objective:

To traversal the winding stone trail within certain time steps(400).



Capacity of the ant: move forward (advance) turn left turn right sense the contents of it facing



Terminal set: T = { ADVANCE, TURN-LEFT, TURN RIGHT}

An individual of S-expression of 7th generation:



It is the exactly the solution for the problem!



Artificial Ant-Santa Fe Trail

Differential Pursuit Game



Two-person, competitive, zero-sum, simultaneous-moving, completeinformation game in which a fast pursuing player P is trying to capture a slower evading player E.

Differnetial Pursuit Game (Cont)

- Objective:
 - To find an optimal strategy for one player when the environment (fitness function) consists of an optimal opponent.
- control variable:
 - at each time step, the choice for each players is the select a value of their control variable. Pursuer: Φ
 - Evader:

Ψ







$F = \{ +, -, *, \%, EXP \}$

The terminal set: T= { X,Y,R} R- ephemeral random constant (-1.0 ~ +1.0)

In 17th generation, a pursuer (the S-expression as following)can capture the evader in 10/10.

S-expression:

(% (- (% (+ (* 2.0 X2) -0.066) -0.365) (% X2 -0.124)) (+ (EXP X1) X2 -0.579)).

S-expression can be depicted graphically as:





Co-Evolution Of A Game

Strategy:

 Definition for co-evolution:
 All species are simultaneously coevolving in a given physical environment

Example:

A plant and inserts



- This is a two player, competitive, complete information, and zero-sum game in which the players make alternating moves(go-left or go-right). Objective: to simultaneously co-evolve strategies
 - for both players.



$F = \{ CXM1, COM1, CXM2, COM2 \}$

- The terminal set:
 T = { L,R}
- variables: XM1,XM2,XM3,OM1,OM2 store the historical information of X or O. consist three values: L, R ,and U.



- Both populations start as random compositions of the available functions and terminals.
- The entire second population servers as the environment for testing the performance of each particular individual in the first population.
- At the same time, the entire first population servers as the environment for testing the performance of each particular individual in the second population.



A best game-playing strategy for player X in 6 generation, the minimax strategy for O servers as the environment. (com2 (com1 (com1 L (com2 L L L) (cxm1 L R L))(cxm1 L L R)) L R) L (com1 L R R)). This strategy simplifies to: (com2 (com1 L L R) L R)

If the player O has been playing its minimax strategy, this S-expression will cause the game to finish at the endpoint with the payoff of 12 to player X, which is the optimal solution.

If the player O was not playing its minimax strategy, this S-expression will cause the game to finish at the endpoints with the payoff of 32,16,or 28 to player X. A best game-playing strategy for player in generation 9, the minimax strategy for X servers as the environment. (cxm2 (cxm1 L (com1 R L L) L) (com1 R L (cxm2 L L R))(com1 L R (cxm1 L R (cxm2 R (com1 L L R) (com1 R L R)))). Can be simplified: (cxm2 (cxm1 # R L) L R)

