cis15 advanced programming techniques, using c++ fall 2007	an example			
lecture # IV.1	• consider the program robot.cpp (posted on the class web page)			
topics:	• this program models a world in which there is a robot and some spots of dirt			
• inheritance	• the robot wanders around looking for spots of dirt and vacuuming them up			
• composition of classes	• this is kind of like the assignment from unit II, where you had a robot running around			
resources:	looking for coins; but as we go through this example, you'll see where the code becomes more sophisticated and more <i>object-oriented</i>			
• Pohl, chapters 8 and 11	• the class definition for the robot class is as follows			
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<pre>class robot {     private:     point location;     int num_vacuumed; public:     robot() { num_vacuumed = 0; }     int getX() const;     int getY() const;     void set( int x, int y );     void set( int x, int y );     void move();     void move();     void move( direction d );     void eat();     bool hungry(); };</pre>	<ul> <li>composition</li> <li>the robot class includes a member of the point class, which we have used before (many times!)</li> <li>we say that the robot class is related to the point class by <i>composition</i></li> <li><i>composition</i> means that one class contains a data member that is an <i>instance</i> of another class, i.e., a data member that is a variable whose data type is another class</li> <li>another example of composition in robot.cpp is that the class world contains both robot and dirt instances</li> </ul>			
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# privacy

• note that several of the function members (methods) of robot look like those for point

- getX()
- getY()

- set( int x, int y )

- print()

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• these function members provide a way to access the values of the data members of the instance of point, which is a data member of robot

• since the data members (x and y) are private, we cannot access them directly in robot — we have to refer to them indirectly by using the public function members of point

# overloading the rest of the methods in the robot class give us the functionality we want from robot, allowing it to move, to vacuum up spots of dirt and to report whether it is busy (i.e., if

- move()
- $\mod d$  )

there are still spots of dirt in the world for it to vacuum)

- vacuum()
- busy()

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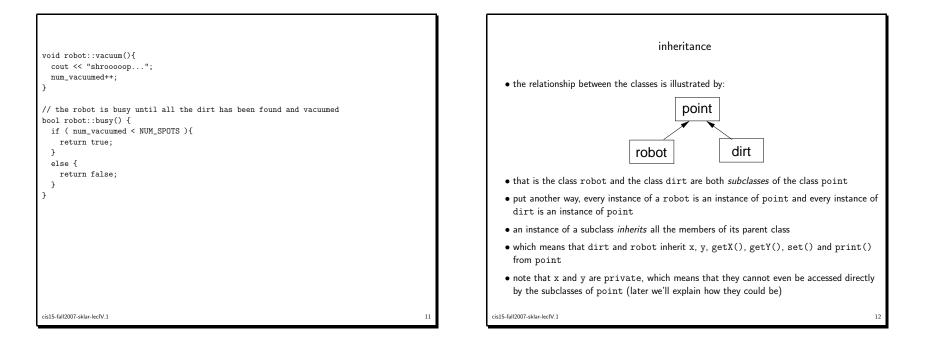
- note that we have two versions of the move() function: one that takes no arguments and one that takes one argument
- creating two versions of the same function, distinguished by their different argument lists, is called *overloading*
- we used overloading when talking earlier in the term about different kinds of constructors

void robot::move(){ direction d; d = static\_cast<direction>( rand() % 4 ); move( d ); // overloaded function void robot::move( direction d ){ int x = location.getX(); int y = location.getY(); switch( d ) { case north: y = (y + 1) % WORLD\_SIZE; break; case south: y = (y - 1);if  $(y < 0) y = WORLD_SIZE;$ break: case east: x = (x + 1) % WORLD\_SIZE; break; case west: x = (x - 1) % WORLD SIZE: if (x < 0) x = WORLD SIZE: break; } location.set( x, y ); cis15-fall2007-sklar-lecIV.1

# extending classes

```
class dirt : public point {
private:
 bool gone;
public:
 dirt() { gone = false; }
 void disappear();
};
void dirt::disappear(){
 cout << "poof!" << endl;</pre>
 gone = true;
class robot : public point {
private:
 int num_vacuumed;
public:
 robot() { num_vacuumed = 0; }
 void move();
 void move( direction d );
 void vacuum();
 bool busy();
};
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```

```
void robot::move(){
 direction d.
 d = static_cast<direction>( rand() % 4 );
 move( d );
// overloaded function
void robot::move( direction d ){
 int x = getX();
 int y = getY();
 switch( d ) {
 case north: y = (y + 1) % WORLD_SIZE;
             break;
 case south: y = (y - 1);
             if (y < 0) y = WORLD_SIZE;
             break;
 case east: x = (x + 1) % WORLD_SIZE;
             break;
 case west: x = (x - 1) % WORLD_SIZE;
             if (x < 0) x = WORLD_SIZE;
             break;
 }
 set( x, y );
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```



```
\bullet normally we want to do more than have a subclass just be a copy of the superclass—like we do with dirt and robot
```

- ${\ensuremath{\bullet}}$  what we often want to do is to have the subclass add things to the superclass
- $\bullet$  (In Java this is explicit. When we define a subclass it is by saying it extends the superclass).
- in our example robot2, the classes dirt and robot are examples of this

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overriding and inheritance

- a subclass definition can re-define a function member defined in the superclass
- this is called *overriding*
- (don't confuse it with *overloading*!)
- we can, for example, override the definition of move in robot
- the program robot3.cpp has:

```
class creature : public point {
  public:
    void move();
    void move(direction d);
};
```

which has two subclasses:

```
class robot : public creature {
  private:
    int num_vacuumed;
```

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- here dirt is extended with:
  - $\mbox{ a private data member gone, which records whether the dirt instance has been vacuumed up yet$
  - a public function member disappear that sets the gone flag to true when a dirt instance has been vacuumed up
- thus dirt has all of the data members of point as well as the additional ones listed here
- as a result we can do this:

dirt spot;
spot.set( 2, 3 );

which calls the set method on the dirt object named spot

• dirt *inherits* the set method from point

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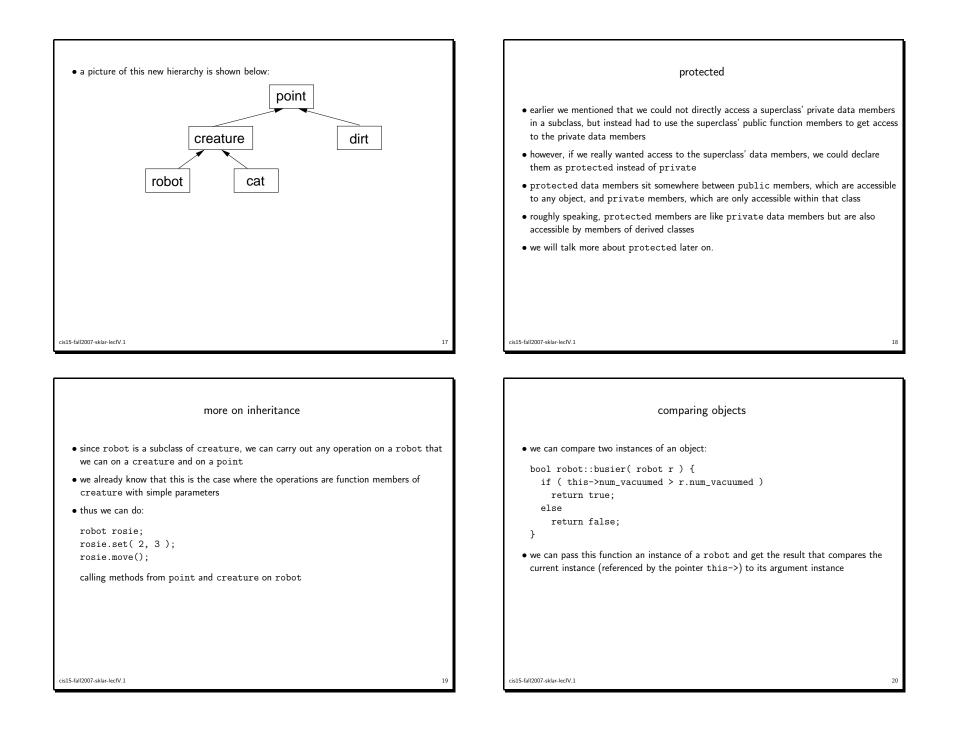
```
public:
  robot() { num_vacuumed = 0; }
  void vacuum();
  bool busy( int num_spots );
};
```

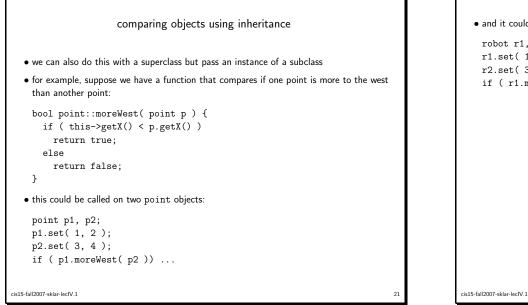
## and

class cat : public creature {
 public:
 void move();
 void move( direction d );
};

• the robot class uses the default move() functions, but the cat class *overrides* the default definitions by providing its own (see the code, but the main difference is that the cat's move() function moves 2 spaces at a time instead of 1)

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robot r1, r2; r1.set( 1, 2 );		
r2.set(3,4);		
if ( r1.moreWest( r2 )) .		

virtual functions and abstract classes • the program robot4.cpp is another version of our world in which we define something called a virtual function • this is the function speak() in the example • notice that this function is first defined in the creature • but the function definition is preceded by the keyword virtual and has a funny prototype: class creature : public point { public: void move(): void move( direction d ); virtual void speak() = 0; }; • because we have defined a virtual function, the class creature is now called *abstract* • we do this when we know we will want to define a function (e.g., speak()) but we don't want to give it any default behavior in the superclass cis15-fall2007-sklar-lecIV.1

- the virtual function speak() in creature will never be called
- because an abstract class can never be instantiated
- it can only be extended, to create other classes
- the other classes, e.g., robot and cat, define their own versions of speak() and then these are not abstract classes but instead can be instantiated
- any class that has at least one pure virtual function is an abstract class
- you cannot create instances of abstract classes! (i.e., you cannot declare variables whose data type is an abstract class)

```
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```

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# summary

 $\bullet$  this lecture has looked at a number of issues related to object oriented programming in C++:

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- composition of classes
- function overloading
- inheritance
- function overriding
- comparing objects
- virtual functions
- abstract classes

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