

On the Size and the Approximability of Minimum Temporally Connected Subgraphs

Dimitris Fotakis

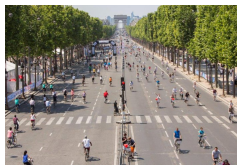
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National Technical University of Athens

Joint work with **Kyriakos Axiotis**, CSAIL, MIT

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Network Properties are Time-Dependent

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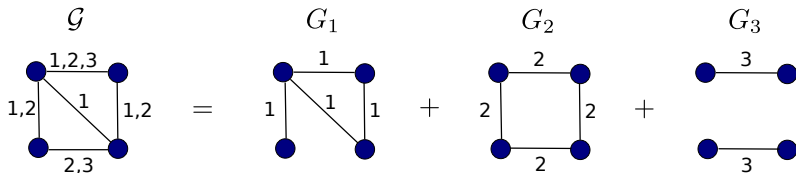
Graphs are used for modeling **networks** (e.g., transportation, communication, social) that are **dynamic** in nature.

- Transportation and communication networks: congestion, maintenance, temporary failures.
- Social networks: relationships evolve with time.
- Networks modelling information spreading, epidemics, dynamical systems, ...



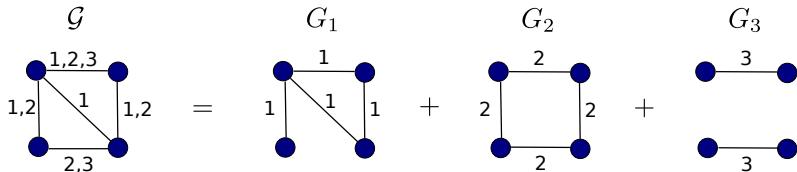
Temporal Graphs

- Generalized model that captures **network changes** over time.
- **Temporal Graph**: sequence $\mathcal{G} = (G_t(V, E_t))_{t \in [L]}$ of (undirected) graphs on vertex set V , edge set E_t varies with time t .
 - Edge e has set of (time)labels l_1, \dots, l_k denoting when e is **available**.



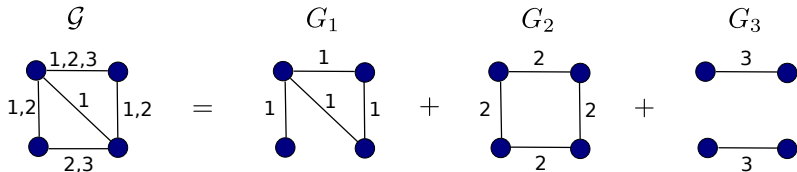
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 - Maximum label L is the **lifetime** of \mathcal{G} .
 - Order $n = |V|$ and size $M = \sum_{t \in [L]} |E_t|$.



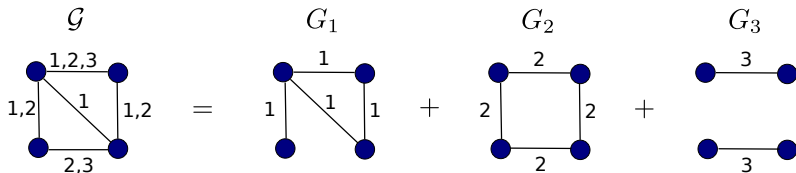
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Temporal Graphs

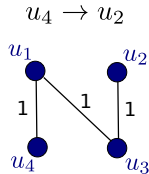
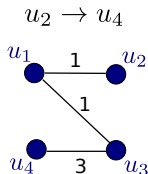
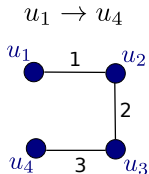
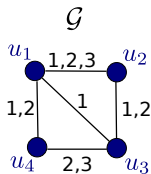
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 - Order $n = |V|$ and size $M = \sum_{t \in [L]} |E_t|$.
 - **Underlying** graph is the union $G(V, \cup_{t \in [L]} E_t)$.
 - \mathcal{G} can be edge (or vertex) **weighted**.
 - **Simple** if every edge available at most once.



Temporal Paths

Temporal $u_1 - u_k$ path: edge labels are **nondecreasing**.

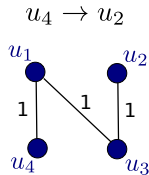
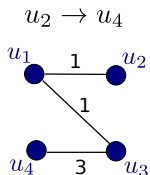
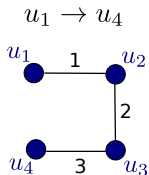
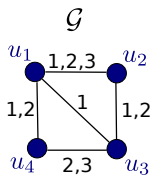
- Temporal path $p = (u_1, (e_1, t_1), u_2, (e_2, t_2), \dots, (e_{k-1}, t_{k-1}), u_k)$, where $t_i \leq t_{i+1}$ and $e_i = \{u_i, u_{i+1}\} \in E_{t_i}$.



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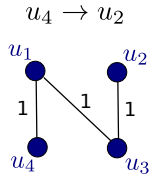
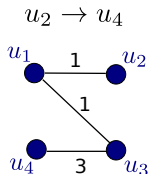
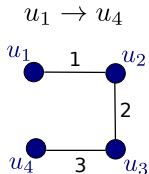
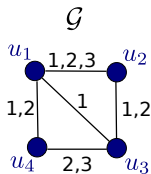
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- Starting at u_1 , we reach u_k by crossing edges only when **available**.
- We can **wait** at any vertex until an adjacent edge is available.
- Crossing an edge is **instant**.



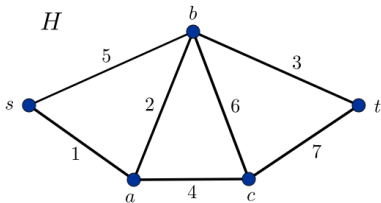
Temporal Connectivity

- \mathcal{G} is **s -temporally connected**, $s \in V$, if exists temporal $s - v$ for any vertex v .
- \mathcal{G} is **temporally connected** if both $u - v$ and $v - u$ temporal paths exist for every vertex pair u, v .



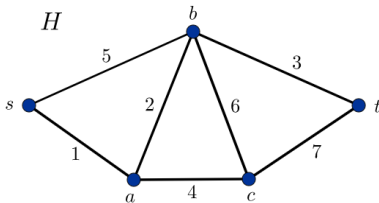
Some Previous Work

- Model, temporal reachability, temporal version of **Menger's theorem** for edge (s, t) -connectivity [Berman 96]
- Menger's theorem for vertex (s, t) -connectivity may **not** hold in temporal graphs [Berman 96], [Kempe Kleinberg Kumar 00]
 - max # vertex disjoint $s - t$ paths = min # vertices whose removal separates s and t .



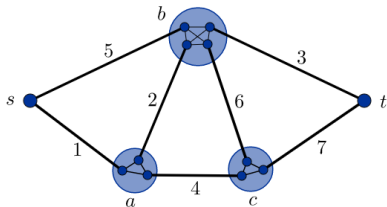
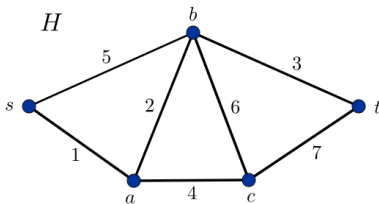
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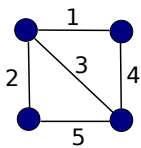
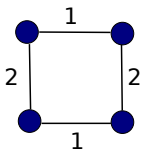
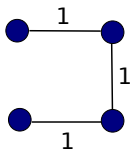
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 - max # vertex disjoint $s - t$ paths = min # vertices whose removal separates s and t .
 - Temporal version holds iff for **any labeling** of graph G , temporal graph \mathcal{G} is **H -minor free**.
- Menger's theorem **holds** if **vertices** are also regarded as **temporal** [Mertziotis Michail Chatzigiannakis Spirakis 13]



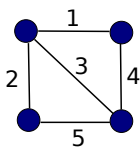
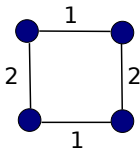
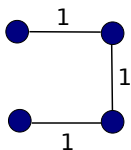
Connectivity Certificates in Temporal Graphs

- **Connectivity certificate**: connected spanning subgraph with **minimum** # edges.
- (Standard) graphs: any **spanning tree**, $n - 1$ edges.



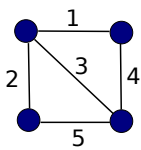
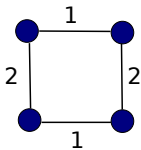
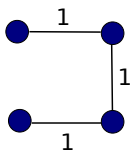
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- **Temporal** graphs: temporal connectivity certificates **more complicated** and of **different size**.



Connectivity Certificates in Temporal Graphs

Upper and lower bounds on size of **temporal** connectivity certificates in worst case (for simple graphs)? [Kempe Kleinberg Kumar 00]

Connectivity Certificates in Temporal Graphs

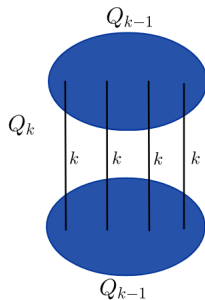
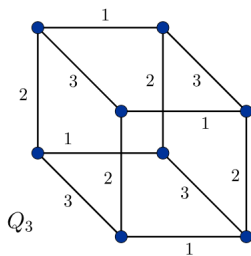
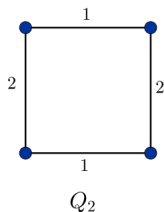
Upper and lower bounds on size of **temporal** connectivity certificates in worst case (for simple graphs)? [Kempe Kleinberg Kumar 00]

- (Trivial) upper bound: $O(n^2)$ (take n different v_i -rooted trees).

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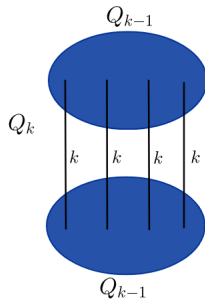
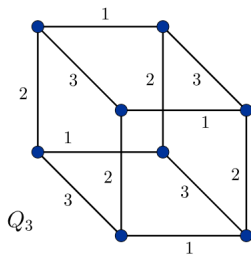
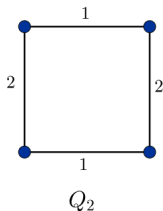
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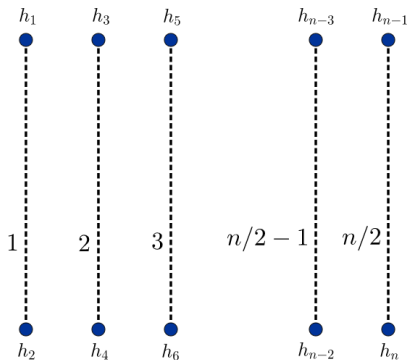
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- We **improve** lower bound to $\Omega(n^2)$!



Quadratic Temporal Connectivity Certificates

Dense temporally connected graph where deletion of any edge breaks temporal connectivity.

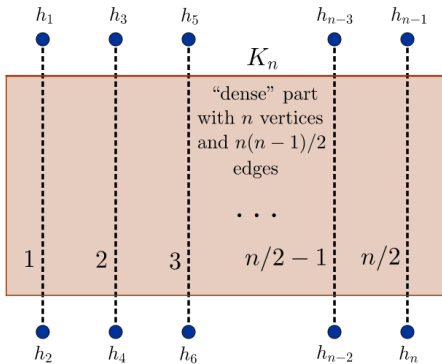
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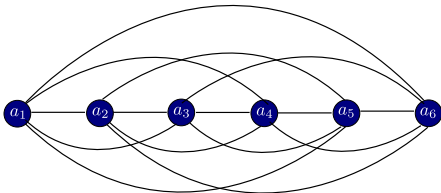
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- Paths use the **same set** of n **intermediate** vertices.



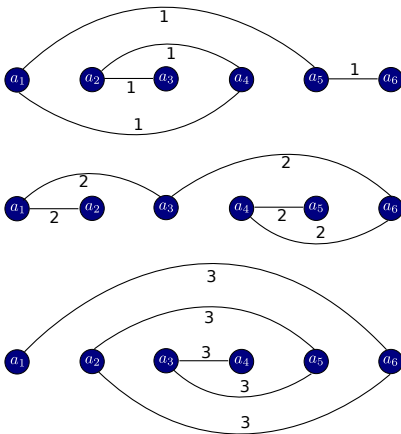
Quadratic Temporal Connectivity Certificates

- Dense part: $n/2$ **edge-disjoint** paths of **length n** on same set of intermediate vertices.
- **Partition** a complete graph K_n into $n/2$ **Hamiltonian paths**.



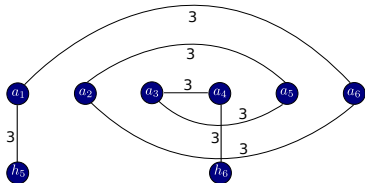
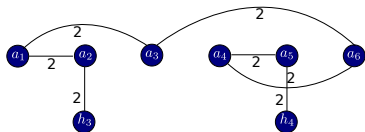
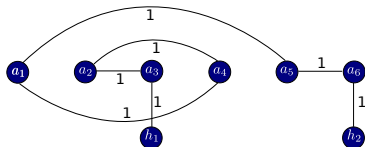
Quadratic Temporal Connectivity Certificates

- Dense part: $n/2$ **edge-disjoint** paths of **length** $n + 1$ on same set of intermediate vertices.
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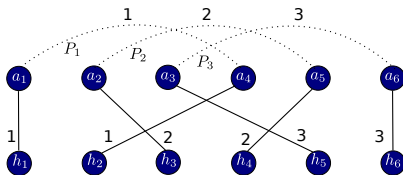
Quadratic Temporal Connectivity Certificates

- Attach 2 new vertices to the endpoints of each Hamilton path.
- All $n + 1$ edges of the i -th Hamilton path have the same label i .



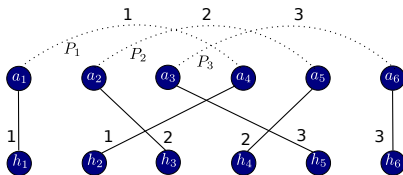
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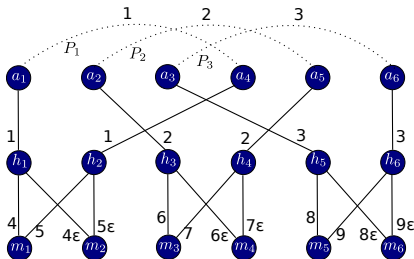
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- Vertices h_1, \dots, h_{2i-2} **unreachable** from vertices h_{2i-1} and h_{2i} .



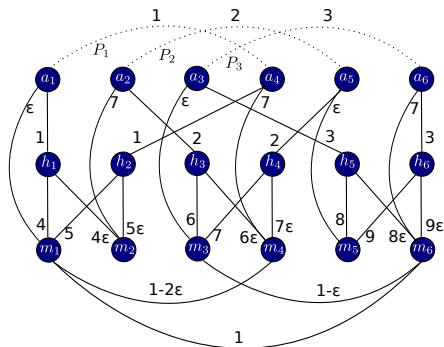
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- **Interconnection** part: connect h -vertices through n additional m -vertices: an m -vertex pair for each Hamilton path.



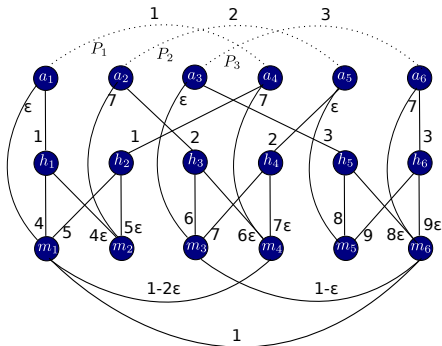
Quadratic Temporal Connectivity Certificates

- **Interconnection** part: connect h -vertices through n additional m -vertices: an m -vertex pair for each Hamilton path.
- Do **not** introduce **alternative** temporal $h_{2i} - h_{2i-1}$ paths (careful use of timelabels).
- m -vertices serve as “**entry**” and “**exit**” points of corresponding Hamilton path.



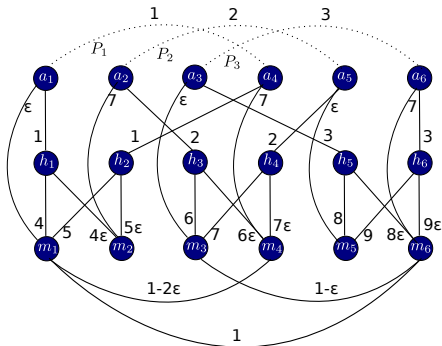
Quadratic Temporal Connectivity Certificates

- Temporal path $h_{2i} - h_{2i-1}$ uses edges with label i only.
- **Removing** any edge with **label i** from i -th Hamilton path **disconnects** h_{2i} from h_{2i-1} .
- All $\Theta(n^2)$ **edges** of “dense part” are needed for connectivity.



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- All $\Theta(n^2)$ **edges** of “dense part” are needed for connectivity.
- **Linear** connectivity certificate by **changing a single label!**



Minimum Temporal Connectivity Certificate

Minimum Temporal Connectivity (MTC)

Given **connected edge-weighted** temporal graph $\mathcal{G}(V, E, w)$, find spanning subgraph $\mathcal{G}'(V, E', w)$, where $E'_t \subseteq E_t$ for all $t \in [L]$, of **minimum total weight** $\sum_{t=1}^L w(E'_t)$ and

- **Minimum s -Temporal Connectivity** (s -MTC): \mathcal{G}' is s -temporally connected.
- **Minimum Temporal Connectivity** (MTC): \mathcal{G}' is (all-pairs) temporally connected.

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Both problems are **hard** to approximate:

- Temporal paths are inherently **directed**.
- Labels restrict relative order of edges in a path.
- Temporal connectivity similar to **Directed Steiner Tree / Forest!**

Minimum s -Temporal Connectivity (s -MTC)

Approximating s -MTC

- Optimal solution is a **tree**: $n - 1$ edges suffice.
- Poly-time solvable in **unweighted** case: temporal BFS.

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- **Weighted** case similar to **Directed Steiner Tree** (DST).

Minimum s -Temporal Connectivity (s -MTC)

Approximating s -MTC

- Optimal solution is a **tree**: $n - 1$ edges suffice.
- Poly-time solvable in **unweighted** case: temporal BFS.
- **Weighted** case similar to **Directed Steiner Tree** (DST).
- Reduction from DST: inapproximable within $O(\log^{2-\varepsilon} n)$, unless $\text{NP} \subseteq \text{ZTIME}(n^{\text{poly} \log n})$ [Halperin Krauthgamer 03]
- Reduction to DST: approximation ratio $O(n^\varepsilon)$, for any $\varepsilon > 0$, and $O(\log^3 n)$ in quasi-P [Charikar et al. 99]

Minimum s -Temporal Connectivity (s -MTC)

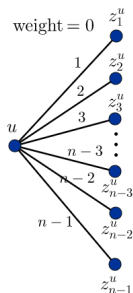
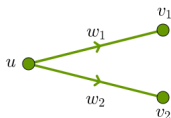
Approximating s -MTC

- Optimal solution is a **tree**: $n - 1$ edges suffice.
- Poly-time solvable in **unweighted** case: temporal BFS.
- **Weighted** case similar to **Directed Steiner Tree** (DST).
- Reduction from DST: inapproximable within $O(\log^{2-\varepsilon} n)$, unless $\text{NP} \subseteq \text{ZTIME}(n^{\text{poly} \log n})$ [Halperin Krauthgamer 03]
- Reduction to DST: approximation ratio $O(n^\varepsilon)$, for any $\varepsilon > 0$, and $O(\log^3 n)$ in quasi-P [Charikar et al. 99]
- Poly-time solvable if underlying graph has **bounded treewidth**.

Reduction from Directed Steiner Tree

Directed graph $H(V_H, E_H, w)$, $|V_H| = n$, source s , set of terminals T .

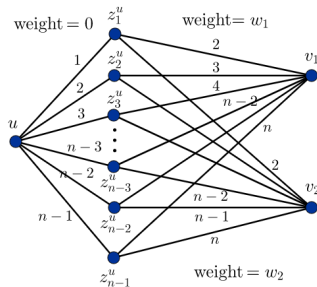
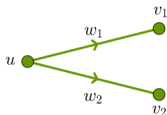
- Every vertex $u \in V_H$ becomes **vertex u** of temporal graph \mathcal{G} .
 - Temporal edges $(\{u, z_u^l\}, l)$ of weight 0, for $l = 1, \dots, n - 1$.



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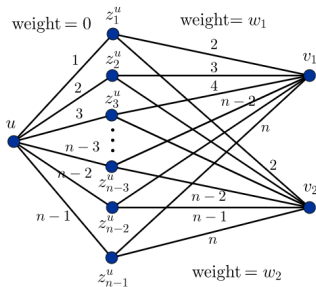
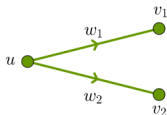
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- s has **“direct” edge** with **label** $n+1$ and weight 0 to every **z-vertex** and to every **non-terminal** vertex.
 - \mathcal{G} has $O(n^2)$ **vertices** and $O(n|E_H|)$ **temporal edges**.



Minimum Temporal Connectivity (MTC)

Approximating Minimum Temporal Connectivity

- Reduction from $(1, 2)$ -Steiner tree: APX-hard for **unweighted** temporal graphs.
- Poly-time solvable if underlying graph is **tree**.
- Approximation ratio **2** if underlying graph is **cycle**.

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- Union of n solutions to v_i -MTC: $O(n^{1+\varepsilon})$ -approximation.
- Reduction to Directed Steiner Forest:
 $O((\Delta M)^{2/3+\varepsilon})$ -approximation [Feldman Kortsarz Nutov 12]

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- Special cases of Minimum Temporal Connectivity where **$O(1)$ -approximation** possible?
- Complexity and approximability if **timelabels** are determined by **simple rules**?

Thank You!